



UNIVERSITY OF COPENHAGEN

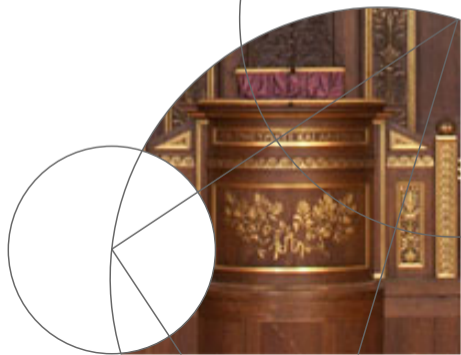


Dataset Condensation

Theory, Practice, and Beyond

ML Section Talk
Tong Chen

March 21, 2024
Slide 1/14



Introduction

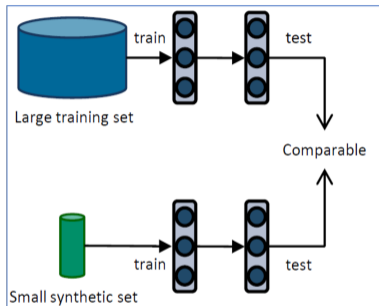


Figure: Dataset Condensation



Problem setting

Given $\mathcal{T} = \{(x_i, y_i)\}_{i=1}^N \subseteq \mathcal{X} \times \mathcal{Y}$, where $(x_i, y_i) \stackrel{i.i.d.}{\sim} \mathbb{P}$.

Find $\mathcal{S} = \{(\tilde{x}_i, \tilde{y}_i)\}_{i=1}^M \subseteq \mathcal{X} \times \mathcal{Y}$, where $(\tilde{x}_i, \tilde{y}_i) \stackrel{i.i.d.}{\sim} \mathbb{Q}$.

$$\mathbb{P} \approx \mathbb{Q}?$$



Notations

Hypothesis space $\mathcal{H} = \{h_\theta : \mathcal{X} \rightarrow \mathcal{Y}\}$.

Loss $l : \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}_+$.

Average loss $L_{\mathbb{P}}(h_\theta) = \mathbb{E}_{(X,Y) \sim \mathbb{P}}[l(h_\theta(X), Y)]$

$$h_{\theta_{\mathbb{P}}}^* = \arg \min_{h_\theta \in \mathcal{H}} L_{\mathbb{P}}(h_\theta), \quad h_{\theta_{\mathbb{Q}}}^* = \arg \min_{h_\theta \in \mathcal{H}} L_{\mathbb{Q}}(h_\theta)$$



Model-based discrepancy

- Loss matching:

$$LM(\mathbb{P}, \mathbb{Q}) = |L_{\mathbb{P}}(h_{\theta_{\mathbb{Q}}}^*) - L_{\mathbb{P}}(h_{\theta_{\mathbb{P}}}^*)|$$



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$$FM(\mathbb{P}, \mathbb{Q}) = \|h_{\theta_{\mathbb{Q}}}^* - h_{\theta_{\mathbb{P}}}^*\|$$



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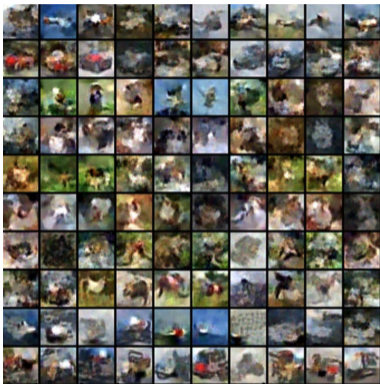
$$FM(\mathbb{P}, \mathbb{Q}) = \|h_{\theta_{\mathbb{Q}}}^* - h_{\theta_{\mathbb{P}}}^*\|$$

- Parameter matching:

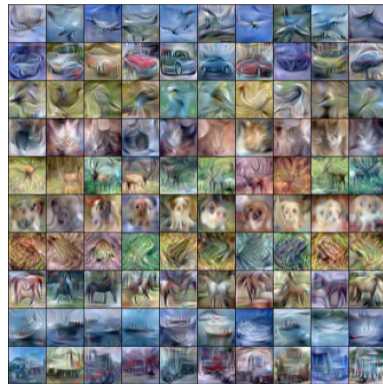
$$PM(\mathbb{P}, \mathbb{Q}) = \|\theta_{\mathbb{Q}} - \theta_{\mathbb{P}}\|$$



Examples



Feature matching



Parameter matching



Model-free discrepancy

- Integral probability metric (IPM):

$$IPM(\mathcal{F}, \mathbb{P}, \mathbb{Q}) = \max_{f \in \mathcal{F}} |\mathbb{E}_{X \sim \mathbb{P}}[f(X)] - \mathbb{E}_{Y \sim \mathbb{Q}}[f(Y)]|$$

- For $\mathcal{F} = \mathcal{C}(\mathcal{X})$,

$$\mathbb{P} = \mathbb{Q} \iff IPM(\mathcal{F}, \mathbb{P}, \mathbb{Q}) = 0$$



Model-free discrepancy

Let \mathcal{H} be the unit ball in an RKHS, with kernel function k ,

- Maximum mean discrepancy (MMD):

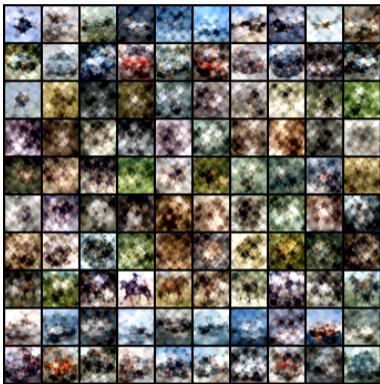
$$\begin{aligned} MMD_k(\mathbb{P}, \mathbb{Q}) &= IPM(\mathcal{H}, \mathbb{P}, \mathbb{Q})^2 \\ &= \mathbb{E}_{X \sim \mathbb{P}} \mathbb{E}_{X' \sim \mathbb{P}} [k(X, X')] - 2 \cdot \mathbb{E}_{X \sim \mathbb{P}} \mathbb{E}_{Y \sim \mathbb{Q}} [k(X, Y)] \\ &\quad + \mathbb{E}_{Y \sim \mathbb{Q}} \mathbb{E}_{Y' \sim \mathbb{Q}} [k(Y, Y')] \end{aligned}$$

- If k is universal,

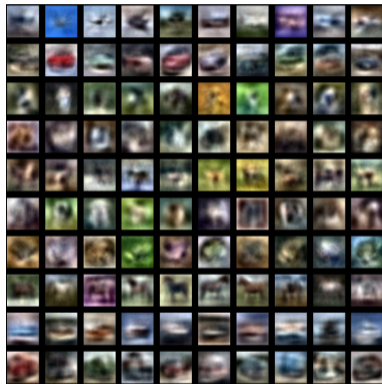
$$\mathbb{P} = \mathbb{Q} \iff MMD_k(\mathbb{P}, \mathbb{Q}) = 0$$



Examples



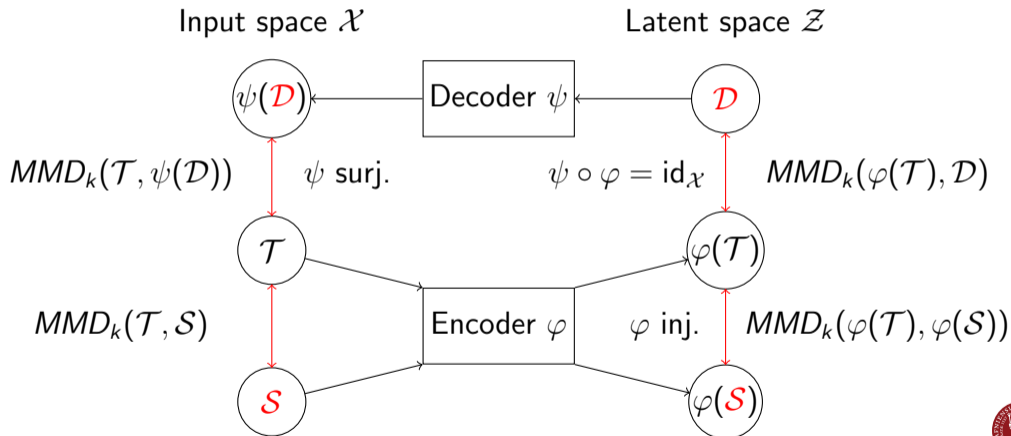
IPM with neural network



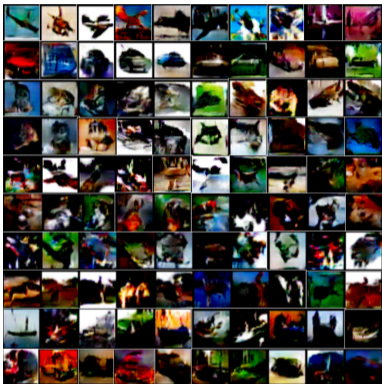
MMD with Gaussian kernel



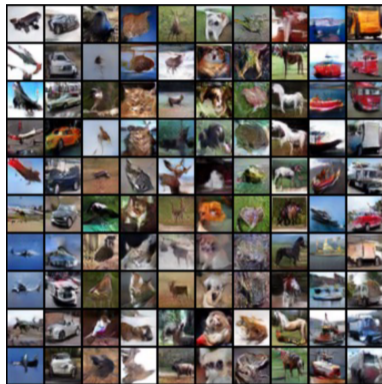
Feature transformation: MMD-GAN



Examples



DC-GAN



DiM

Beyond dataset condensation

- Various optimization goal: accuracy, robustness, efficiency, fairness, privacy, trustworthy, etc.



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- Adversarial loss:

$$L_{\mathbb{P}, \varepsilon}^{adv}(h_{\theta}) = \mathbb{E}_{(X, Y) \sim \mathbb{P}} \left[\max_{\|\delta\| \leq \varepsilon} l(h(X + \delta), Y) \right]$$



Beyond dataset condensation

- Various optimization goal: accuracy, robustness, efficiency, fairness, privacy, trustworthy, etc.
- Adversarial loss:

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- Generate robust features:

$$\min_{\mathbb{Q}} L_{\mathbb{P},\varepsilon}^{adv}(h_{\theta_{\mathbb{Q}}}^*), \text{ s.t. } h_{\theta_{\mathbb{Q}}}^* = \arg \min_{h_{\theta} \in \mathcal{H}} L_{\mathbb{Q}}(h_{\theta})$$



Robust data condensation

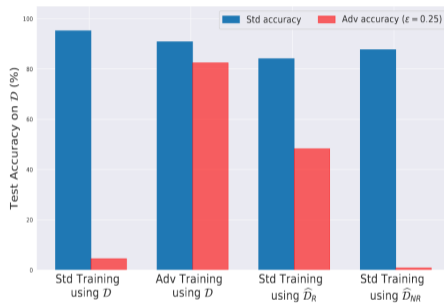


Figure: Robust and non-robust data for standard training



Thank you!

